

Read “Introduction to Differential Geometry” up to Chapter 4.

1. Suppose you lived on a small sphere of radius  $R$ , so that spherical geometry was more natural than planar geometry. What formulas would children be taught in school instead of the Euclidean formulas  $C = 2\pi r$  (for circumference of a circle) and  $A = \pi r^2$  (for area of a circle)?
2. Recall that in the hyperbolic plane (the upper half-plane model  $H = \{(x, y) : y > 0\}$ ) of hyperbolic geometry, “lines” are either semicircles centered on the  $x$ -axis or vertical lines, as shown in Figure 1.5.

Show that for any two points  $(x_1, y_1)$  and  $(x_2, y_2)$  on the hyperbolic plane there is a unique hyperbolic line passing through the points; compute it explicitly.

3. In standard spherical coordinates on  $S^2$ , with  $x = \sin \theta \cos \phi$ ,  $y = \sin \theta \sin \phi$ , and  $z = \cos \theta$ , show that  $\sin^2 \theta$  is a smooth function on the sphere (because it is the restriction of a smooth function on  $\mathbb{R}^3$ ), but that  $\sin^2 \phi$  is not a smooth function on the sphere. (Hint: what does it look like near the north pole in  $(x, y)$  coordinates?)
4. Consider two possible bases for  $\mathbb{R}^2$ :

$$e_1 = \begin{pmatrix} 5 \\ 2 \end{pmatrix} \quad \text{and} \quad e_2 = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \quad \text{vs.} \quad f_1 = \begin{pmatrix} 2 \\ -3 \end{pmatrix} \quad \text{and} \quad f_2 = \begin{pmatrix} 1 \\ -2 \end{pmatrix}.$$

- (a) Find the transformation matrix  $P$  such that  $f_i = \sum_{j=1}^2 p_i^j e_j$ , and the transformation matrix  $Q$  such that  $e_i = \sum_{j=1}^2 q_i^j f_j$ .
  - (b) How would you express the vector  $v = 7e_1 - 3e_2$  in the  $\{f\}$ -basis?
5. A linear operator  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  is given in the standard basis  $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$  by

$$T = \begin{pmatrix} 1 & -1 & 2 \\ 0 & 2 & -2 \\ -1 & 0 & -1 \end{pmatrix}.$$

- (a) If you think of the domain and range of  $T$  as *different* vector spaces, show how to change the bases of both to get  $T$  in reduced row echelon form. (Describe the new bases explicitly.)
  - (b) If you think of the domain and range of  $T$  as the *same* vector space, show how to change the basis to get  $T$  in Jordan form.
6. Prove directly, imitating Proposition 3.3.1, that if  $T: V \rightarrow V$  is a linear operator, then the number  $\text{Tr}(T^2) = \sum_{i=1}^n \sum_{j=1}^n T_i^j T_j^i$  does not depend on choice of basis.